EASTERN UNIVERSITY, SRI LANKA
SECOND EXAMINATION IN SCIENCE 200 $2 q$ qni

## April./May.'2004

Repeat
MT 201 - VECTOR SPACES AND MATRICES

## Answer four questions

Time: Two hours

Q1. (a) Define what is meant by
(i) a vector space;
(ii) a subspace of a vector space.

Let $V$ be a vector space over a field $F$ and $W$ be a non-empty subset of $V$. Prove that $W$ is a subspace of $V$ if and only if $a x+b y \in W$ for every $x, y \in W$ and for every $a, b \in F$.
(b) Let $W_{1}$ and $W_{2}$ be two subspaces of a vector space $V$ over a field $F$ and let $A_{1}$ and $A_{2}$ be non-empty subsets of $V$. Show that
(i) $W_{1}+W_{2}$ is the smallest subspace containing both $W_{1}$ and $W_{2}$;
(ii) if $A_{1}$ spans $W_{1}$ and $A_{2}$ spans $W_{2}$ then $A_{1} \cup A_{2}$ spans $W_{1}+W_{2}$.
(c) Let $V$ be the vector space of all functions from real field $\mathbb{R}$ into $\mathbb{R}$. Which of the following subsets are subspaces of $V$ ? Justify your answer.
(i) $W_{1}=\{f \in V: f(3)=0\}$
(ii) $W_{2}=\{f \in V: f(7)=f(1)\}$
(iii) $W_{3}=\{f \in V: f(-x)=f(x), \forall x \in \mathbb{R}\}$
(iv) $W_{4}=\{f \in V: f(7)=2+f(1)\}$.

Q2. (a) Define the following:
i. A linearly independent set of vectors;
ii. A basis for a vector space;
iii. Dimension of a vector space.
(b) Let $V$ be an $n$-dimensional vector space.

Show that:
i. A linearly independent set of vectors of $V$ with $n$ elements is a basis for $V$;
ii. Any linearly independent set of vectors of $V$ may be extended as a basis for $V$;
iii. If $L$ is a subspace of $V$, then there exists a subspace $M$ of $V$ such that $V=L \oplus M$;
iv. Extend the subset $\{(1,2,-1,1),(0,1,2,-1)\}$ to a basis for $\mathbb{R}^{4}$.
(State any results you may use)

Q3. (a) Define:
(i) Range space $R(T)$;
(ii) Null space $N(T)$

of a linear transformation $T$ from a vector space $V$ in to another vector space $W$.
Find $R(T), N(T)$ of the linear transformation $T: \mathbb{R}^{3} \rightarrow \mathbb{R}^{3}$, defined by:

$$
T(x, y, z)=(2 x+y+3 z, 3 x-y+z,-4 x+3 y+z)
$$

Verify the equation $\operatorname{dim} V=\operatorname{dim}(R(T))+\operatorname{dim}(N(T))$ for this linear transformation.
(b) Let $T: \mathbb{R}^{3} \rightarrow \mathbb{R}^{3}$ be a linear transformation defined by: $T(x, y, z)=(x+2 y, x+y+z, z)$ and let $B_{1}=\{(1,0,0),(0,1,0),(0,0,1)\}$ and $B_{2}=\{(1,1,0),(0,1,1),(1,0,1)\}$ be bases for $\mathbb{R}^{3}$. Find:
(i) the matrix representation of $T$ with respect to the basis $B_{1}$;
(ii) the matrix representation of $T$ with respect to the basis $B_{2}$ by using the transition matrix;
(iii) the matrix representation of $T$ with respect to the basis $B_{2}$ directly.

Q4. (a) Define the following terms
(i) Rank of a matrix;
(ii) Echelon form of a matrix;
(iii) Row reduced echelon form of a matrix.
(b) Let $A$ be an $m \times n$ matrix. Prove that
(i) row rank of $A$ is equal to column rank of $A$;
(ii) if $B$ is an $m \times n$ matrix obtained by performing an elementary row operation on $A$, then $r(A)=r(B)$.
(c) Find the rank of the matrix

$$
\left(\begin{array}{ccccc}
1 & 3 & 1 & -2 & -3 \\
1 & 4 & 3 & -1 & -4 \\
2 & 3 & -4 & -7 & -3 \\
3 & 8 & 1 & -7 & -8
\end{array}\right)
$$

(d) Find the row reduced echelon form of the matrix

$$
\left(\begin{array}{cccccc}
1 & 1 & 1 & 1 & -1 & 1 \\
1 & 1 & 3 & 3 & 0 & 2 \\
2 & 1 & 3 & 3 & -1 & 3 \\
2 & 1 & 1 & 1 & -2 & 4
\end{array}\right)
$$

Q5. (a) Define the following terms as applied to an $n \times n$ matrix $A=\left(a_{i j}\right)$.
(i) Cofactor $A_{i j}$ of an element $a_{i j}$,
(ii) Adjoint of $A$.

Prove that

$$
A \cdot(\operatorname{adj} A)=(\operatorname{adj} A) \cdot A=\operatorname{det} A \cdot I
$$

where $I$ is the $n \times n$ identity matrix.
(b) If $A$ and $B$ are two $n \times n$ non-singular matrices, then prove that
(i) $\operatorname{adj}(\alpha A)=\alpha^{n-1} \cdot \operatorname{adj} A$ for every real number $\alpha$,
(ii) $\operatorname{adj}(A B)=(\operatorname{adj} B)(\operatorname{adj} A)$;
(iii) $\operatorname{adj}\left(A^{-1}\right)=(\operatorname{adj} A)^{-1}$;
(iv) $\operatorname{adj}(\operatorname{adj} A)=(\operatorname{det} A)^{n-2} A$;
(v) $\operatorname{adj}(\operatorname{adj}(\operatorname{adj} A))=(\operatorname{det} A)^{n^{2}-3 n+3} A^{-1}$.
(c) Find the inverse of the matrix


$$
\left[\begin{array}{ccc}
-1 & 2 & -3 \\
2 & 1 & 0 \\
4 & -2 & 5
\end{array}\right]
$$

Q6. (a) State the necessary and sufficient condition for a system of linear equations to be consistent.

Reduce the augmented matrix of the following system of linear equations to its row reduced echelon form and hence determine the conditions on $a, b, c, d, e$ and f such that the system has;
(i) a unique solution;
(ii) no solution;
(iii) more than one solution.

$$
\begin{aligned}
& a x+b y=e \\
& c x+d y=f
\end{aligned}
$$

(b) State and prove Crammer's rule for $3 \times 3$ matrix and use it to solve:

$$
\begin{array}{r}
2 x_{1}-5 x_{2}+2 x_{3}=7 \\
x_{1}+2 x_{2}-4 x_{3}=3 \\
3 x_{1}-4 x_{2}-6 x_{3}=5
\end{array}
$$

(c) The system of equations,

$$
\begin{aligned}
2 x+3 y+z & =5 \\
3 x+2 y-4 z+7 t & =k+4 \\
x+y-z+2 t & =k-1
\end{aligned}
$$

is known to be consistent. Find the value of $k$ and the general solution of the system.

