

EASTERN UNIVERSITY, SRI LANKA DEPARTMENT OF MATHEMATICS SECOND EXAMINATION IN SCIENCE - 2008/2009 FIRST SEMESTER (Feb./Mar., 2010) MT 201 - VECTOR SPACES AND MATRICES

Answer all questions

Time: Three hours

- 1. Define the term *subspace* of a vector space.
 - (a) Let $V = \{f/f : \mathbb{R} \to \mathbb{R}, f(x) > 0, \forall x \in \mathbb{R}\}$. For any $f, g \in V$ and for any $\alpha \in \mathbb{R}$ define an addition \oplus and a scalar multiplication \odot as follows:

$$(f \oplus g)(x) = f(x).g(x), \forall x \in \mathbb{R}$$

and

$$(\alpha \odot f)(x) = (f(x))^{\alpha}.$$

Prove that (V, \oplus, \odot) is a vector space over the set of real numbers \mathbb{R} .

- (b) i. Let V be a vector space over a field \mathbb{F} . Prove that a non-empty subset W of V is a subspace of V if and only if $\alpha x + \beta y \in W$, for any $x, y \in W$ and $\alpha, \beta \in \mathbb{F}$.
 - ii. Let $P_n = \left\{ \sum_{i=0}^n a_i x^i : a_i \in \mathbb{R} \right\}$ be the set of all polynomials of degree $\leq n$ with real coefficients. Prove that P_n is a subspace of the vector space $V = \left\{ \sum_{i=0}^n a_i x^i : a_i \in \mathbb{R}, n \in \mathbb{N} \right\}$, the set of all polynomials with real coefficients.

Is it true that the set of polynomials exactly of degree n is a subspace of V? Justify your answer.

- 2. Define what is meant by *dimension* of a vector space.
 - (a) Let V be an n-dimensional vector space.

Show that

- i. a linearly independent set of vectors of V with n elements is a basis for V_i
- ii. any linearly independent set of vectors of V may be extended to a basis for V;
- iii. if $\{e_1, e_2, \dots, e_n\}$ is a basis for V then $V = \langle \{e_1, e_2, \dots, e_r\} \rangle \oplus \langle \{e_{r+1}, e_{r+2}, \dots \forall r \in \{1, 2, \dots, n-1\}.$
- (b) i. Let w = (1, -1, 0, 3), x = (2, 1, 1, -1), y = (4, -1, 1, 3), z = (1, -4, -1, 8] be vectors in ℝ⁴ and let S = ({w, x, y, z}). Find a basis and the dimension of S. Is the set {w, x, y, z} linearly independent? Extend the basis of S that you obtained to a basis for ℝ⁴. Find also a basis of S ∩ T, where T {(x₁, x₂, x₃, x₄) : x₁ + x₂ + x₃ + x₄ = 0] is a subspace of ℝ⁴.

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ii. Let $\{x_1, x_2, \dots, x_n\}$ be any vectors in a vector space. Let $A = \langle \{x_1, x_2, \dots, x_n, x_{n+1}\} \rangle$. Prove that dim $B = \dim A + \epsilon$, where is 0 if $x_{n+1} \in A$ and 1 if $x_{n+1} \notin A$.

3. (a) Let $D: P_n(t) \to P_{n-1}(t)$, the derivative operator, be defined by

$$D(p(t)) = a_1 + 2a_2t + \dots + na_nt^{n-1}$$

where $p(t) = a_0 + a_1 t + a_2 t^2 + \dots + a_n t^n$ and $P_n(t)$ is the set of all polynomia of degree less than or equal to n. Show that D is a linear transformation. Find the matrix representation of D with respect to the bases $\{1, t, t^2, \dots, t^n\}$ and $\{1, 1 + t, t + t^2, \dots, t^{n-2} + t^{n-1}\}$ of $P_n(t)$ and $P_{n-1}(t)$ respectively. (b) If the matrix representation of a linear transformation

 $T: P_3(t) \to P_3(t)$ with respect to the bases $\{1 - t, t - t^2, t^2 - t^3, t^3\}$ and $\{1, 1 + t, t + t^2, t^2 + t^3\}$ is

$$\begin{pmatrix} 1 & -1 & 1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 \\ -1 & 1 & 1 & 1 \end{pmatrix}$$

then determine T.

(c) Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be a linear transformation defined by

$$T(x, y, z) = (x + 2y, x + y + z, z)$$

and let $B_1 = \{(1, 1, 1), (1, 2, 3), (2, -1, 1)\}$ and $B_2 = \{(1, 1, 0), (0, 1, 1), (1, 0, 1)\}$ be bases for \mathbb{R}^3 . Find the matrix representation of T with respect to the basis B_2 by using the transition matrix.

4. Define what is meant by *rank* of a matrix.

(a) Let A be an $m \times n$ matrix. Prove the following:

(i) row rank of A is equal to column rank of A;

(ii) if B is a matrix obtained by performing an elementary row operation on

A, then A and B have the same rank.

(b) Find the rank of the matrix

$$\begin{pmatrix} 1 & 1 & 2 & 0 \\ 2 & a+1 & 3 & a-1 \\ -3 & a-2 & a-5 & a+1 \\ a+2 & 2 & a+4 & -2a \end{pmatrix}$$

for each possible value of the scalar a.

(c) Find the row reduced echelon form of

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- 5. (a) Define the following terms as applied to an $n \times n$ matrix $A = (a_{ij})$.
 - (i) cofactor A_{ij} of an element a_{ij} ;
 - (ii) adjoint of A.

Prove with the usual notations that

$$A \cdot (adjA) = (adjA) \cdot A = detA \cdot I,$$

where I is the $n \times n$ identity matrix.

- (b) Prove that if B is a matrix obtained from a square matrix A by
 - (i) multiplying a row of A by a scalar $\alpha \neq 0$ then $detB = \alpha detA$.
 - (ii) interchanging two rows of A, then detB = -detA.
- (c) Let A be an n-square matrix with all elements equal to a. Prove that

i.
$$det(A + \lambda I) = \lambda^{n-1}(na + \lambda);$$

ii. $(A + \lambda I)^{-1} = \frac{1}{\lambda(na + \lambda)} \begin{bmatrix} (n-1)a + \lambda & -a & \cdots & -a \\ -a & (n-1)a + \lambda & \cdots & -a \\ \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots \\ -a & -a & \cdots & (n-1)a + \end{bmatrix}$

6. (a) State the necessary and sufficient condition for a system of linear equations to be consistent.

Reduce the augmented matrix of the following system of linear equations

$$a_{11}x_1 + a_{12}x_2 = b_1$$
$$a_{21}x_1 + a_{22}x_2 = b_2$$

to its row reduced echelon form and hence determine the conditions on non-zero scalars $a_{11}, a_{12}, a_{21}, a_{22}, b_1$ and b_2 such that the system has

- (i) a unique solution;
- (ii) no solution;
- (iii) more than one solution.

(b) Show that the system of equations



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is consistent, for all values of b if $c \neq 1$. Find the value of b for which the system is consistent if c = 1 and obtain the general solution for these values.

(c) State and prove Crammer's rule for 3×3 matrix and use it to solve

 $3x_1 + x_2 + x_3 = 3$ $3x_1 + 2x_2 + 2x_3 = 5$ $2x_1 - 3x_2 - 2x_3 = 1.$